

# Introduction to optimisation

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## Exercise 1

Let  $\phi : \mathbb{R}^K \rightarrow \mathbb{R} \cup \{+\infty\}$  be closed and  $\mu$ -strongly convex. Use the Reciprocity formula to show why the Fenchel conjugate of  $\phi$  must be  $\frac{1}{\mu}$  strongly convex.

**Solution:**

Fenchel conjugate:  $\phi^*(x^*) = \sup_{x \in \mathbb{R}^N} \{x^* \cdot x - f(x)\}$ .

Completely forgot the Reciprocity formula.

In all the follows, we consider the problem  $\mathcal{P}$  of minimizing a continuous and  $\mu$ -strongly convex function  $f : \mathbb{R}^N \rightarrow \mathbb{R}$  on  $V = \{x \in \mathbb{R}^N : Ax = b\}$  where  $A \in \mathbb{R}^{M \times N}$  and  $b \in \mathbb{R}^M$

## Exercise 2

Why can we assure that  $\mathcal{P}$  has a unique solution?

**Solution:**

Since  $f$  is strongly convex, we see that the minimization problem of  $f$ , has a unique solution. And this minimization problem is given by  $\mathcal{P}$ .

## Exercise 3

Use the first order optimality condition to show that  $\hat{x}$  is a solution of  $\mathcal{P}$  iff  $A\hat{x} = b$  and there exists  $\hat{y} \in \mathbb{R}^M$  s.t.  $-A^T\hat{y} \in \partial f(\hat{x})$ . We say  $(\hat{x}, \hat{y})$  is an optimal pair.

Since  $f$  is continuous, we have  $\partial(f + \iota_V) = \partial f + \partial \iota_V = \partial f + \text{ran}(A^T)$ . You do not need to prove this.

**Solution:**

For a general function  $\beta : \mathbb{R}^N \rightarrow \mathbb{R}$  we see that if  $\beta$  is convex, then  $\tilde{x}$  is a minimum if  $0 \in \partial\beta(\tilde{x})$ .

Since  $f$  is strictly convex, so  $f + \iota_V$  is strictly convex we see that there is a unique

minimizer, which we call  $\hat{x}$ , so we see that  $0 \in \partial(f + \iota_V)(\hat{x})$ .

Note that this means that  $0 \in (\partial f + \text{ran}(A^T))(\hat{x})$ . But we see that  $\partial \iota_V(x) = \text{ran}(A^T)$  only if  $x \in V$ . Therefore we see that we must have  $\hat{x} \in V$  so  $A\hat{x} = b$ .

Therefore  $0 \in \partial f(\hat{x}) + \text{ran}(A^T)$ . This means that  $-\text{ran}(A^T) \in \partial f(\hat{x})$ .

Note that  $-A^T \hat{y} \in -\text{ran}(A^T)$  so therefore we get indeed that  $-A^T \hat{y} \in \partial f(\hat{x})$ .

In the rest of the exam, we shall establish the convergence of a sequence  $(x_k, y_k)$ , constructed from an initial point  $(x_0, y_0) \in \mathbb{R}^N \times \mathbb{R}^M$  by iterating

$$\begin{cases} x_{k+1} &= \arg \min\{L(x, y_k) : x \in \mathbb{R}^N\} \\ y_{k+1} &= y_k + \alpha(Ax_{k+1} - b) \end{cases}$$

with  $\alpha > 0$  and  $L(x, y) = f(x) + y \cdot (Ax - b) = f(x) + (A^T y) \cdot x - y \cdot b$  for each  $(x, y) \in \mathbb{R}^N \times \mathbb{R}^M$ .

## Exercise 4

Why is  $x_{k+1}$  well defined?

**Solution:**

Since  $f$  is well-defined, and matrix multiplication is well defined, we see that  $L(x, y)$  is well-defined. Since  $\arg \min(K(\cdot))$  is only well defined if the thing inside the min brackets is well defined (so  $K(\cdot)$ ), we see that  $\arg \min\{L(x, y_k) : x \in \mathbb{R}^N\}$  is well defined.

## Exercise 5

Write the optimality condition satisfied by  $x_{k+1}$  (this comes from the first subiteration).

**Solution:**

First note that since  $f$  is convex, we have that  $L(x, y_k)$  is convex for a fixed  $y_k$  on the set  $V$ .

We see that if  $\hat{x} \in V$  minimizes  $f$ , it also minimizes  $L(x, y_k)$ . Note that  $L(x, y_k)$  is also differentiable at  $\hat{x}$ .

Therefore we see that since we want that  $L(\hat{x}, y_k) \leq L(x, y_k)$  for all  $x \in V$ , we must have by Fermat's rule that  $\nabla L(\hat{x}, y_k) \cdot (x - \hat{x}) \geq 0, \forall x \in V$ .

Note that  $\nabla L(x, y_k) = \nabla f(x) + A^T y_k$ . Therefore we must have that  $(\nabla f(\hat{x}) + A^T y_k) \cdot (x - \hat{x}) \geq 0$  for all  $x \in V$ .

## Exercise 6

Show that the dual  $\mathcal{D}$  of the problem  $\mathcal{P}$  is  $\min\{h(y) : y \in \mathbb{R}^M\}$  where  $h(y) = f^*(-A^T y) + b \cdot y$

**Solution:**

Note that we can write  $\mathcal{P}$  as  $f(x) + g(x)$  where  $g(x) = \iota_V(x)$  and  $f(x)$  as in the equation. Therefore we see that the dual is given by

$$\inf_{y \in \mathbb{R}^M} \{f^*(-P^T y) + g^*(y)\} \quad P \in \mathbb{R}^{M \times N}$$

Take  $P = A$ , so then we see that the dual is given by

$$\inf_{y \in \mathbb{R}^M} \{f^*(-A^T y) + g^*(y)\}$$

If we can show that  $g^*(y) = b \cdot y$ , we see that we are done.

Since  $g(x) = \iota_V(x)$  we see that  $g^*(x) = \sup\{x \cdot z \mid z \in V\}$ . Note that if  $z \in V$  then  $Az = b$ . So we have that  $g^*(x) = \sup\{x \cdot z \mid Az = b\}$ .

## Exercise 7

Compute  $\nabla h$  and verify that  $h$  is  $l$ -smooth with  $l = \frac{\|A\|^2}{\mu}$ .

**Solution:**

We see that  $h$  is  $l$ -smooth if there exists  $l > 0$  s.t.  $\|\nabla h(z) - \nabla h(y)\| \leq l\|z - y\|, \forall z, y \in V$ . Now let  $k(y) = -A^T y$ , so we see that  $h(y) = f^*(k(y)) + b \cdot y$ . Therefore we see that

$$\begin{aligned} \nabla h(y) &= \nabla f^*(y)|_{k(y)} \cdot \nabla k(y) + b \cdot \nabla y \\ &= \nabla f^*(y)|_{k(y)} \cdot -A^T + b \\ &= -\nabla f^*(y)|_{k(y)} \cdot A^T + b \end{aligned}$$

Therefore we see that

$$\begin{aligned} \|\nabla h(z) - \nabla h(y)\| &= \|-\nabla f^*(x)|_{k(z)} \cdot A^T + b - (-\nabla f^*(x)|_{k(y)} \cdot A^T + b)\| \\ &= \| -A^T (\nabla f^*(x)|_{k(z)} - \nabla f^*(x)|_{k(y)}) \| \\ &\leq \|A\| \cdot \|\nabla f^*(x)|_{k(z)} - \nabla f^*(x)|_{k(y)}\| \end{aligned}$$

Now use question 1. we see that  $f$  is  $\mu$  smooth, so  $f^*$  is  $\frac{1}{\mu}$ -smooth, so we get

$$\begin{aligned} \|\nabla f^*(x)|_{k(z)} - \nabla f^*(x)|_{k(y)}\| &\leq \frac{1}{\mu} \|k(z) - k(y)\| \\ &= \frac{1}{\mu} \| -A^T z + A^T y \| \leq \frac{\|A\|}{\mu} \|z - y\| \end{aligned}$$

If we substitute this back we get indeed

$$\|\nabla h(z) - \nabla h(y)\| \leq \frac{\|A\|^2}{\mu} \|z - y\|$$

### Exercise 8

Show that the sequence  $(y_k)$  satisfies  $y_{k+1} = y_k - \alpha \nabla h(y_k)$

**Solution:**

So it is enough to show that  $-\alpha \nabla h(y_k) = \alpha(Ax_{k+1} - b)$  so  $\nabla h(y_k) = b - Ax_{k+1}$

We see that  $\nabla h(y) = -\nabla f^*(z)|_{z=-A^T y} \cdot A^T + b$ . Therefore we get that  $\nabla h(y_k) = -\nabla f^*(z)|_{z=-A^T y_k} \cdot A^T + b$ . Therefore we see that it is enough to show that  $\nabla f^*(z)|_{z=-A^T y_k} \cdot A^T = Ax_{k+1}$ . But since I do not see how to work with  $\nabla f^*(z)$  I do not see how to continue.

### Exercise 9

For which values of  $\alpha$  can we guarantee that the sequence  $(x_k, y_k)$  converges to an optimal pair  $(\hat{x}, \hat{y})$  as  $k \rightarrow \infty$ . Express the result in terms of  $\mu$  and  $\|A\|$ .

**Solution:**

We see that  $(x_k, y_k) \rightarrow (\hat{x}, \hat{y})$  as  $k \rightarrow \infty$  if  $\|(\hat{x} - x_k) + (\hat{y} - y_k)\| \xrightarrow{k \rightarrow \infty} 0$ .

Furthermore if  $y_k \rightarrow \hat{y}$  as  $k \rightarrow \infty$  then we see that  $\|y_{k+1} - y_k\| \rightarrow 0$  as  $k \rightarrow \infty$ .

So  $\|-\alpha \nabla h(y_k)\| \rightarrow 0$  as  $k \rightarrow \infty$ .

$$\|\nabla h(y_{k+1}) - \nabla h(y_k)\| \leq \frac{\|A\|^2}{\mu} \|y_{k+1} - y_k\| = \frac{\|A\|^2}{\mu} \|\alpha(Ax_{k+1} - b)\| = \frac{\|A\|^2 |\alpha|^2}{\mu} \|Ax_{k+1} - b\|$$

Now use that we want that  $x_{k+1} \rightarrow \hat{x}$  so  $Ax_{k+1} - b \rightarrow 0$ . So we have convergence if  $\frac{\|A\|^2 |\alpha|^2}{\mu} < 1$ . Therefore we must have that  $\alpha < \frac{\sqrt{\mu}}{\|A\|}$ .

### Exercise 10

What can you say about the convergence rate of this algorithm?

**Solution:**

The larger we make  $\|A\|$ , the faster this function converges. Note that  $\mu$  is fixed for a certain  $f$ .